

Théorie des goupilles de raquette**Théorie avancée des goupilles de raquette****Perturbation de marche due à une goupille flexible**

Caractéristiques du spiral avec une spire externe semi-circulaire

➔ Référence : E:\Résonateur (TA)\Data\Bal_spiral plat (ex num).mcd(R)

Dimensions	$\epsilon p = 0.03 \text{ mm}$	$ha = 0.15 \text{ mm}$	$S = 4.5 \times 10^{-3} \text{ mm}^2$
$d2_{sp} = 4.52 \text{ mm}$	$d1_{sp} = 1.1 \text{ mm}$	$p_{sp} = 0.135 \text{ mm}$	$n_{sp} = 12.667$
$L_{sp} = 11.182 \text{ cm}$	$\psi_0 := 2 \cdot \pi \cdot n_{sp}$	$\psi_0 = 4.56 \times 10^3 \text{ deg}$	$E = 2.093 \times 10^{11} \text{ m}^{-2} \text{ N}$
Position du piton	$r_P := 0.5 \cdot d_{\text{piton}}$	$\alpha_P := 0$	$x_P := r_P \cdot \cos(\alpha_P) \quad y_P := r_P \cdot \sin(\alpha_P)$
	$x_P = 2.55 \text{ mm}$	$y_P = 0 \text{ mm}$	$z_P := x_P + i \cdot y_P$
Position du point d'attache à la virole	$r_V := 0.5 \cdot d1_{sp}$	$\alpha_V(\theta) := \psi_0 + \theta$	$x_V(\theta) := r_V \cdot \cos(\alpha_V(\theta)) \quad y_V(\theta) := r_V \cdot \sin(\alpha_V(\theta))$
Position du point de raccordement sur le spiral		$\alpha_A := 180 \cdot \text{deg}$	$r_A := 0.5 \cdot d2_{sp} \quad z_A := r_A \cdot e^{i \cdot \alpha_A}$
Spire externe formée d'un demi-cercle	$R_0 := r_P$	$x_{0t}(\alpha_t) := R_0 \cdot \cos(\alpha_t) \quad y_{0t}(\alpha_t) := R_0 \cdot \sin(\alpha_t)$	$z_{0t}(\alpha_t) := R_0 \cdot e^{i \cdot \alpha_t}$
	$s_t(\alpha_t) := R_0 \cdot \alpha_t$	$l_t := s_t(\alpha_A)$	$l_t = 8.011 \text{ mm}$

Forme initiale du spiral

$$a := \frac{p_{sp}}{2 \cdot \pi} \quad r_s(\alpha) := r_A - a \cdot (\alpha - \alpha_A) \quad x_{0s}(\alpha) := r_s(\alpha) \cdot \cos(\alpha) \quad y_{0s}(\alpha) := r_s(\alpha) \cdot \sin(\alpha)$$

$$s_s(\alpha) := \frac{1}{2 \cdot a} \cdot (r_A^2 - r_s(\alpha)^2) \quad s_s(\alpha) := r_A \cdot (\alpha - \alpha_A) - \frac{a}{2} \cdot (\alpha - \alpha_A)^2 \quad L_t := s_s(\psi_0 + \alpha_A) + l_t$$

$$L_t = 11.983 \text{ cm}$$

Position angulaire des goupilles par rapport au piton:

$$\epsilon := 0.06 \quad s_g := \epsilon \cdot L_t \quad s_g = 7.19 \text{ mm} \quad \alpha_g := \frac{s_g}{R_0} \quad \alpha_g = 161.548 \text{ deg}$$

Amplitude stationnaire du balancier $\theta_0 = 270 \text{ deg}$ Elongations de contact spiral - goupille $\theta_1 := 20 \cdot \text{deg}$

Raideur de la goupille

➔ Référence : E:\Résonateur (TA)\Data\Masse_vol - Coef_th - Mod_E.mcd(R)

$$E_g := E_{\text{aiton}} \quad E_g = 1 \times 10^5 \text{ N} \cdot \text{mm}^{-2} \quad d_g := 0.1 \cdot \text{mm} \quad l_g(\lambda) := \lambda \cdot d_g$$

$$k(\lambda) := \frac{3 \cdot \pi \cdot E_g \cdot d_g}{64 \cdot \lambda^3} \quad k(100) = 1.473 \text{ m}^{-1} \text{ N} \quad \kappa(\lambda) := \frac{E \cdot I_s}{k(\lambda) \cdot R_0^3}$$

Calcul du facteur \mathcal{F}

$$x_{0g}(\alpha_g) := R_0 \cdot \cos(\alpha_g) \quad y_{0g}(\alpha_g) := R_0 \cdot \sin(\alpha_g) \quad x_g := x_{0g}(\alpha_g) \cdot m^{-1} \quad y_g := y_{0g}(\alpha_g) \cdot m^{-1}$$

$$\xi_{0g}(\alpha_g) := \frac{R_0}{\alpha_g} \cdot \sin(\alpha_g) \quad \eta_{0g}(\alpha_g) := \frac{R_0}{\alpha_g} \cdot (1 - \cos(\alpha_g))$$

$$\Delta_g(\alpha_g) := \frac{R_0^4}{4 \cdot \alpha_g^3} \cdot (\alpha_g - \sin(\alpha_g)) \cdot [\alpha_g \cdot (\alpha_g + \sin(\alpha_g)) - 4 \cdot (1 - \cos(\alpha_g))] \quad \Delta_g(\alpha_g) = 1.237 \text{ mm}^4$$

$$W_{c2}(\alpha_g) := \frac{E \cdot I_s \cdot R_0^3}{8 \cdot \Delta_g(\alpha_g) \cdot \alpha_g^3} \cdot [3 \cdot \alpha_g^2 - 2 \cdot \alpha_g \cdot \sin(\alpha_g) \cdot (2 + \cos(\alpha_g)) - (1 - \cos(\alpha_g)) \cdot (1 - 7 \cdot \cos(\alpha_g))]$$

$$N(\alpha_g) := \frac{E \cdot I_s}{2 \cdot R_0 \cdot \alpha_g \cdot W_{c2}(\alpha_g)} \quad N(\alpha_g) = 0.131$$

$$a(\alpha_g) := \frac{4 \cdot N(\alpha_g)}{N(\alpha_g) - 1} \cdot \left[\frac{\alpha_g^2 - 2 \cdot \alpha_g \cdot \sin(\alpha_g) + 2 \cdot (1 - \cos(\alpha_g))}{(\alpha_g - \sin(\alpha_g)) \cdot [\alpha_g \cdot (\alpha_g + \sin(\alpha_g)) - 4 \cdot (1 - \cos(\alpha_g))]} \right]$$

$$b(\alpha_g) := \frac{8 \cdot \alpha_g \cdot N(\alpha_g)}{\alpha_g \cdot (\alpha_g + \sin(\alpha_g)) - 4 \cdot (1 - \cos(\alpha_g))}$$

$$c(\alpha_g) := \frac{4 \cdot \alpha_g \cdot N(\alpha_g)}{(\alpha_g - \sin(\alpha_g)) \cdot [\alpha_g \cdot (\alpha_g + \sin(\alpha_g)) - 4 \cdot (1 - \cos(\alpha_g))]}$$

$$\mathcal{F}(\alpha_g, \lambda) := \frac{1 - \kappa(\lambda) \cdot a(\alpha_g)}{1 + \kappa(\lambda) \cdot b(\alpha_g) + \kappa(\lambda)^2 \cdot c(\alpha_g)} \quad \mathcal{F}(\alpha_g, 100) = 0.555$$

Facteur de modification de la perturbation de marche dans le cas d'une goupille flexible

$$\lambda_m := 8, 9 \dots 300$$



